

# PicoMite Stepper Motor Control Reference

## 1. Overview

The STEPPER command provides a comprehensive system for controlling up to 3 stepper motor axes (X, Y, Z) with support for G-code execution, acceleration planning, and hardware limit switches.

Note: This functionality is only implemented in the RP2350 versions of the PicoMite firmware.

## 2. Initialization & Configuration

### 2.1 Initialization

```
STEPPER INIT [arc_tolerance] [,buffer_size]
```

Initializes the stepper subsystem. Must be called before any other STEPPER commands.

- arc\_tolerance: (Optional) Tolerance for arc segmentation in mm (default: 0.05).
- buffer\_size: (Optional) Size of the G-code lookahead buffer (default: 16, max: 256).

### 2.2 Axis Configuration

```
STEPPER AXIS axis, step_pin, dir_pin [, enable_pin] [, dir_invert] [, steps_per_mm] [, max_vel] [, max_accel]
```

Configures a specific axis (X, Y, or Z).

- axis: X, Y, or Z.
- step\_pin/dir\_pin: GPIO pins for Step and Direction signals.
- enable\_pin: (Optional) GPIO pin for Enable signal (active low).
- dir\_invert: (Optional) 1 to invert direction, 0 otherwise.
- steps\_per\_mm: (Optional) Steps required to move 1mm.
- max\_vel: (Optional) Maximum velocity in mm/min.
- max\_accel: (Optional) Maximum acceleration in mm/s<sup>2</sup>.

### 2.3 Limits & Safety

```
STEPPER HWLIMITS x_min, y_min, z_min [,x_max] [,y_max] [,z_max]
```

Configures hardware limit switch pins (active low).

```
STEPPER LIMITS axis, min_mm, max_mm
```

Sets soft limits for an axis in mm.

```
STEPPER ESTOP
```

Emergency stop: halts motion immediately, clears buffer, and disables drivers.

## 3. Motion Control

### 3.1 G-Code Execution

```
STEPPER GC <gcode> [words...]
```

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Executes a standard G-code command string.

Supported codes: G0, G1, G2, G3, G28, G90, G91, G92, M3, M5. Example:

STEPPER GC G1 X10 Y5 F500

```
STEPPER GCODE G0|G1|G2|G3 [, X, x] [, Y, y] [, Z, z] [, F, feed] [, I, i] [, J, j] [, R, r]
```

Alternative syntax for adding motion commands to the buffer. All parameters must be comma separated.

Example: STEPPER GCODE G1, X, 10, Y, 5, F, 500

## 3.2 Manual Positioning

```
STEPPER POSITION HOME
```

Sets all axes to position 0 and clears G92 offsets.

```
STEPPER POSITION axis, position
```

Sets the current position of an axis to the specified value (mm).

## 4. Advanced Features

```
STEPPER SCURVE 0|1
```

Enables (1) or disables (0) S-curve acceleration profiling for smoother motion.

```
STEPPER JERK value
```

Sets the jerk limit in mm/s<sup>3</sup> for S-curve planning.

```
STEPPER SPINDLE pin [,invert]
```

Configures a spindle control pin.

## 5. System Management

```
STEPPER RUN
```

Arms the system and begins executing buffered commands.

```
STEPPER CLEAR
```

Clears the G-code buffer (only when motion is idle).

```
STEPPER STATUS
```

Displays detailed system status, including axis positions, buffer state, and configuration.

```
STEPPER CLOSE
```

Shuts down the stepper subsystem and releases resources.*Page 2*